

## YEAR 12 MATHEMATICS SPECIALIST **SEMESTER ONE 2017 QUESTIONS OF REVIEW 3:**

Vectors in 3 dimensions

G

C

By daring & by doing

Name: Solutions

F

B

Thursday 11th May

Time: 40 minutes

Mark

P

D

0

/30

E

A

Calculator allowed.

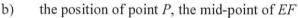
1. [6 marks - 1, 1, 2 and 2]

> The right rectangular prism shown has vertices O(0,0,0), A(3,0,0), C(0,4,0) and D(0,0,2).

Use appropriate vector methods to represent:



$$(0,4,2)$$
 or  $\overrightarrow{06} = \begin{bmatrix} 0\\4\\2 \end{bmatrix}$ 



$$\frac{7}{0} = \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} \quad \text{or} \quad (3,2,2)$$

an equation for the line through points C and P c)

$$\frac{3}{7} = \begin{bmatrix} 0 \\ 4 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}$$
 or equivalent suches 
$$\begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} + \mu$$

$$\begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} + \mu \begin{bmatrix} -3 \\ 2 \\ -2 \end{bmatrix}$$

the angle the line CP makes with the base OABC d)

$$\overrightarrow{CX} = \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix}$$
angle  $\left(\begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}\right) = 29^{\circ}$  or  $0.506^{\circ}$ 

else 
$$[\vec{a} \cdot \vec{b}] = |\vec{c}| |\vec{b}| |\cos \theta$$
  
 $\Rightarrow |\cos \theta| = \frac{13}{\sqrt{13} \cdot \sqrt{17}} = 0.8745$ 

Use  $\overrightarrow{OA} \otimes \overrightarrow{OB}$  and the vectors  $\overrightarrow{OA} = 3i - 4j + k$  and  $\overrightarrow{OB} = 5i + 4j - 2k$  to calculate

a) the area of  $\triangle OAB$ 

$$|A\times B| = |A||B| \sin \theta$$

$$\Rightarrow \text{ area} = \frac{1}{2} \left| \overrightarrow{OA} \times \overrightarrow{OB} \right| = \frac{1}{2} \left| \begin{bmatrix} 4 \\ 11 \\ 32 \end{bmatrix} \right| = 17.0 \text{ wints}$$

$$\Rightarrow \text{ or } 3\sqrt{129}$$

b) ∠AOB

$$\sin \theta = \frac{34.07}{\sqrt{26.345}} = 0.9961$$

Sperk

3. [9 marks - 1, 3, 2, 2 and 1]

a) Express the vector equation 
$$\left| \vec{r} - \begin{bmatrix} 1 \\ 3 \\ 1.5 \end{bmatrix} \right| = \frac{9}{2}$$
 in Cartesian form

b) Calculate the point(s) of intersection of 
$$\vec{r} = \begin{bmatrix} 5 \\ 1 \\ 2 \end{bmatrix} + \lambda \begin{bmatrix} 8 \\ -4 \\ 1 \end{bmatrix}$$
 and  $|\vec{r} - \begin{bmatrix} 1 \\ 3 \\ 1.5 \end{bmatrix}| = \frac{9}{2}$ 

Substitute: 
$$\begin{bmatrix} 5+8\lambda-1 \\ 1-4\lambda-3 \\ 2+\lambda-1.5 \end{bmatrix} = \frac{9}{2}$$

c) Describe, by a suitable vector or algebraic equation, the locus of points that are equidistant from the points of intersection found in (b)

Place through the midst (1,3,1.5) 
$$\perp$$
 [8]

d) Show that  $\vec{r} = \begin{bmatrix} 5 \\ 1 \\ 2 \end{bmatrix} + \lambda \begin{bmatrix} 8 \\ -4 \\ 1 \end{bmatrix}$  is a diameter of  $\begin{vmatrix} \vec{r} - \begin{bmatrix} 1 \\ 3 \\ 1.5 \end{vmatrix} = \frac{9}{2}$ 

e) Calculate the distance between any pair of parallel planes tangential to both sides of

$$\left| \vec{r} - \begin{bmatrix} 1 \\ 3 \\ 1.5 \end{bmatrix} \right| = \frac{9}{2}$$

4. [7 marks - 2, 2 and 3]

The vector 
$$\begin{bmatrix} a \\ b \\ 1 \end{bmatrix}$$
 is perpendicular to the plane  $\Gamma_1$ , which is itself parallel to both  $\begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix}$  and

$$\begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}$$
.

a) Use scalar (dot) product calculations to set up equations sufficient to evaluate a and b

$$\begin{bmatrix} a \\ b \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} = 0 \Rightarrow 2a + 3b - 1 = 0$$

$$\begin{bmatrix} a \\ b \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix} = 0 \Rightarrow -a + b + 3 = 0$$

b) Use a vector (cross) product calculation to set up an equation to evaluate a and b

$$\begin{bmatrix} 2\\3\\1 \end{bmatrix} \times \begin{bmatrix} -1\\1\\3 \end{bmatrix} = k \begin{bmatrix} 2\\5\\1 \end{bmatrix} \Rightarrow 9+1 = ka$$

$$1-6 = kb$$

$$but 6-1 = 5 = k$$

Solve for a and b and hence develop a Cartesian equation for  $\Gamma_1$ , which passes through

(1,2,3) 
$$Sa = 10 \qquad a = 2 \\ Sb = -5 \qquad b = -1$$

or simple ready...

i. plane is 
$$\frac{7}{7}$$
.  $\begin{bmatrix} 2\\ -1\\ 1 \end{bmatrix}$  =  $C = 3$ 

## 5. [4 marks]

The position vectors of three non-collinear points A, B and C, with respect to an origin O, are  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$  respectively.

O does not lie in the plane ABC.

The point Q with position vector  $\mathbf{q} = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$  does lie in the plane ABC.

Show that  $\alpha + \beta + \gamma = 1$ 

Plane is 
$$\hat{x} = a + \lambda (a - b) + \mu(b - c)$$
 sor similar.  
 $q = \alpha a + \beta b + \delta c$ 

$$\Rightarrow$$
  $\alpha = 1 + \lambda$   
 $\beta = -\lambda + \mu$   
 $\gamma = -\mu$ 

adding: X+ B+8=1

## Formulae:

## Vectors

Magnitude:

$$|(a_1, a_2, a_3)| = \sqrt{a_1^2 + a_2^2 + a_3^2}$$

Dot product:

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}||\mathbf{b}|\cos\theta = a_1b_1 + a_2b_2 + a_3b_3$$

Triangle inequality:

$$|\mathbf{a} + \mathbf{b}| \leq |\mathbf{a}| + |\mathbf{b}|$$

Vector equation of a line in space:

one point and the slope:

$$\mathbf{r} = \mathbf{a} + \lambda \mathbf{b}$$

two points A and B:

$$\mathbf{r} = \mathbf{a} + \lambda(\mathbf{b} - \mathbf{a})$$

Cartesian equations of a line in space:

$$\frac{x - a_1}{b_1} = \frac{y - a_2}{b_2} = \frac{z - a_3}{b_3}$$

Parametric form of vector equation of

a line in space:

$$x = a_1 + \lambda b_1$$
.....(1)  
 $y = a_2 + \lambda b_2$ .....(2)  
 $z = a_3 + \lambda b_3$ .....(3)

$$y = a_1^1 + \lambda b_2^1 \dots (2)$$

$$z = a_1^2 + \lambda b_2^2 \dots (3)$$

Vector equation of a plane in space:

$$\mathbf{r} \cdot \mathbf{n} = c$$

$$r = a + \lambda b + \mu c$$

Cartesian equation of a plane:

$$ax + by + cz = d$$

Vector cross product

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \times \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{bmatrix} \quad \text{and} \quad |\vec{a} \times \vec{b}| = |\vec{a}| |\vec{b}| \sin \theta$$

The sphere defined by  $|\vec{r} - \vec{a}| = k$  has a centre with position vector  $\vec{a}$  and radius k